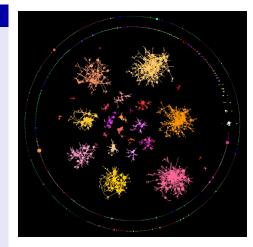
# On Adjacency and e-Adjacency in General Hypergraphs: Towards a New e-Adjacency Tensor 2nd IMA CTCDM Derby 14.09.2018

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# Background

## Ideas behind

- Ranking of vertices in graphs => random walks
- RW for hypergraphs exist
- Diffusion = local process
   => knowledge of the neighbourhood.
- Study of diffusion process => Laplacian
- Incidence and adjacency matrices keep only pairwise information
- Pairwise adjacency is too restrictive for hypergraphs
- Higher order adjacency requires tensor
- Laplacian tensor is linked to the adjacency tensor
- Adjacency tensor for uniform hypergraph is known Cooper and Dutle [2012]



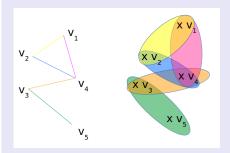
## Key points

- Rigourous definition of adjacency in hypergraphs
- A proposal for an e-adjacency tensor interpretable in term of hypergraph uniformisation

- Two processes are designed:
  - a hypergraph uniformisation process (HUP)
  - a polynomial homogeneisation process (PUP)

# Hypergraphs

## From graphs to hypergraphs



- Hypergraphs = generalisation of graphs to multiple vertex links
- Hypergraphs introduced by Berge and Minieka [1973].

#### Definition

Bretto [2013]: A hypergraph  $\mathcal{H}$  on a finite set  $V = \{v_1; v_2; ...; v_n\}$  is a family of hyperedges  $E = \{e_1, e_2, ..., e_p\}$  where each hyperedge is a non-empty subset of V.

#### Two visions

- set of elements of power set of vertices → set view
- extension of graphs ~> n-adic relationship view

# k-uniform hypergraph

All its hyperedges have same cardinality k.

## In graphs

Two vertices are said adjacent if it exists an edge linking them => pairwise relationship

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- Vertices incident to one given edge are said e-adjacent.
   => also pairwise relationship
- e-adjacency and adjacency are equivalent in graphs

## Extending to hypergraphs

- k vertices are said k-adjacent if it exists a hyperedge that hold them
   => multi-adic relationship
- Vertices of a given hyperedge are said to be e-adjacent.
   => multi-adic relationship
- k-adjacency: maximal k-adjacency that can be found in a given hypergraph
- In *k*-uniform hypergraph: equivalence *k*-adjacency and e-adjacency.

In general hypergraphs: the equivalence doesn't hold anymore!

#### Cooper and Dutle (k-)adjacency tensor

■ ([Author's note]: **degree normalized** *k*-)adjacency tensor: Cooper and Dutle [2012]  $\mathcal{A} = (a_{i_1...i_k})_{1 \le i_1...,i_k \le n}$  such that:

$$a_{i_1\ldots i_k} = \frac{1}{(k-1)!} \begin{cases} 1 & \text{if } \left\{ v_{i_1}, ..., v_{i_k} \right\} \in E \\ 0 & \text{otherwise.} \end{cases}$$

Allows to retrieve degree of vertices:

$$\deg\left(v_{i}\right) = \sum_{i_{2},\ldots,i_{k}=1}^{n} a_{ii_{2}\ldots i_{k}}.$$

Allows to have hypergraph spectral theory Qi and Luo [2017]

# Tensor for general hypergraphs: the art of filling



What about this?



#### => We need to store additional information

#### Banerjee e-adjacency tensor

Let  $\mathcal{H} = (V, E)$  with  $V = \{v_1, v_2, ..., v_n\}$  and family  $E = \{e_1, e_2, ..., e_p\}$ . Let  $k_{\max} = \max\{|e_i| : e_i \in E\}$  be the maximum cardinality of the family of hyperedges. The ([Author's note]: **e-) adjacency hypermatrix** of  $\mathcal{H}$  written  $\mathcal{A}_{\mathcal{H}} = (a_{i_1...i_{k_{\max}}})_{1 \leqslant i_1,...,i_{k_{\max}} \leqslant n}$  is such that for a hyperedge:  $e = \{v_{l_1}, ..., v_{l_s}\}$  of cardinality  $s \leqslant k_{\max}$ .

$$a_{p_1...p_{k_{\max}}} = \frac{s}{\alpha}, \text{ where } \alpha = \sum_{\substack{k_1,...,k_s \ge 1 \\ \sum k_i = k_{max}}} \frac{k_{\max}!}{k_1!...k_s!}$$

with  $p_1, ..., p_{k_{\max}}$  chosen in all possible way from  $\{l_1, ..., l_s\}$  with at least once from each element of  $\{l_1, ..., l_s\}$ .

# Why an other proposal?

#### **Motivations**

- The e-adjacency tensor should be easily interpretable:
  - in term of e- and k-adjacency
  - in term of the way it is built
- Information on k-adjacency should be easy to gather
- Can we really fill a tensor without transforming its spectra?

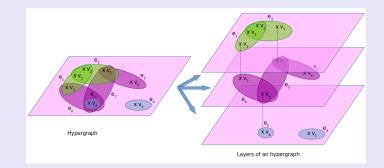
#### Requirements

The tensor should be:

- invariant to vertex permutations either globally or at least locally.
- allow the retrieval of the hypergraph in its original form.
- the sparsest possible in between two possible choices.
- allow the retrieval of the degrees of the nodes
- store the information of e-adjacency and k-adjacency

# Layers I

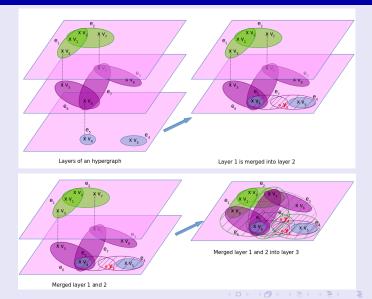
# Decomposition of the hypergraph in layers



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# Filling and merging

# Iterative process on layers



# Hypergraph uniformisation process

#### Two elementary operations

#### y-vertex-augmentation operation.

- add a vertex to each hyperedge of a given hypergraph
- *y*-vertex-augmented hypergraph  $\overline{\mathcal{H}_{\overline{w}}} = \left(\overline{V}, \overline{E}, \overline{w}\right)$  of  $\mathcal{H}_w$

#### merging operation:

- merges two weighted hypergraphs  $\mathcal{H}_a = (V_a, E_a, w_a)$  and  $\mathcal{H}_b = (V_b, E_b, w_b)$
- obtained: merged hypergraph  $\widehat{\mathcal{H}_{w}} = \left(\widehat{V}, \widehat{E}, \widehat{w}\right)$

#### The hypergraph uniformisation process

- Transform each  $\mathcal{H}_k$  into a weighted hypergraph  $\mathcal{H}_{w_k,k} = (V, E_k, w_k) w_k(e) = c_k$ => dilatation coefficient: keep the generalized hand-shake lemma
- Iterates over a two-phase step:
  - the inflation phase
  - the merging phase

### Symmetric hypermatrices and homogeneous polynomials

 Symmetric cubical hypermatrices are bijectively mapped to homogeneous polynomials Comon et al. [2015]

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Use the hypermatrix multilinear matrix multiplication Lim [2013].

$$\begin{array}{l} \mathcal{H}_{k} => A_{k} = \left(a_{(k) \ i_{1} \dots i_{k}}\right) \\ \hline (z)_{[k]} = (z, \dots, z) \in (\mathbb{R}^{n})^{k}, \ (z)_{[k]} . A_{k} \text{ contains only one element:} \\ P_{k} \ (z_{0}) = \sum_{1 \leqslant i_{1}, \dots, i_{k} \leqslant n} a_{(k) \ i_{1} \dots i_{k}} z^{i_{1}} \dots z^{i_{k}}. \end{array}$$

As  $A_k$  is symmetric:  $P_k(z_0) = \sum_{1 \leq i_1 \leq \ldots \leq i_k \leq n} \alpha_{(k) i_1 \ldots i_k} z^{i_1} \ldots z^{i_k}$  with  $\alpha_{(k) i_1 \ldots i_k} = k! \alpha_{(k) i_1 \ldots i_k}$ .

# Polynomial uniformisation process I

## Principle

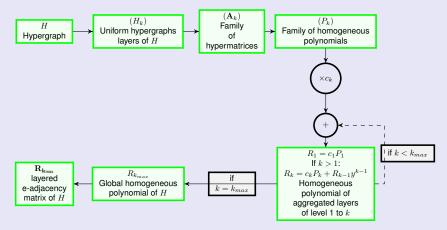


Figure 1: Different phases of the construction of the e-adjacency tensor

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#### **Details**

$$R_{k+1}(z_k) = y^{k(k+1)} \left( R_k \left( \frac{z_{k-1}}{y^{k(k)}} \right) + c_{k+1} P_{k+1} \left( \frac{z_o}{y^{k(k+1)}} \right) \right)$$
  
=  $R_k (z_{k-1}) y^k + c_{k+1} \sum_{i_1, \dots, i_{k+1}=1}^n a_{(k+1) i_1 \dots i_{k+1}} z^{i_1} \dots z^{i_{k+1}}$ 

# Definition of the hypermatrix of layer of level k

$$R_{k}\left(w_{(k)}\right) = \sum_{i_{1},...,i_{k}=1}^{n+k-1} r_{(k) \ i_{1} \dots i_{k}} w_{(k)}^{i_{1}} \dots w_{(k)}^{i_{k}} \text{ where:}$$

$$for \ i \in [\![n]\!]: w_{(k)}^{i} = z^{i} \text{ and for } i \in [\![n+1; n+k-1]\!]: w_{(k)}^{i} = y^{i-n}$$

$$for \ all \ \forall j \in [\![k]\!], \text{ for } 1 \leqslant i_{1} < \dots < i_{j} \leqslant n, \text{ for all } l \in [\![j+1; k]\!]^{1}: i_{l} = n+l-1 \text{ and, for all } \sigma \in \mathcal{S}_{k}:$$

$$r_{(k) \ \sigma(i_{1}) \dots \sigma(i_{k})} = \frac{c_{j} \alpha_{(j) \ i_{1} \dots i_{j}}}{k!} = \frac{j!}{k!} c_{j} a_{(j) \ i_{1} \dots i_{j}}$$

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• otherwise  $r_{(k) i_1 \dots i_k}$  is null.

<sup>1</sup>With the convention  $\llbracket p,q \rrbracket = \emptyset$  if p > q

## Choice of dilatation coefficient

We choose:  $c_j = \frac{k_{\max}}{j}$  to allow the generalized hand-shake lemma to hold.  $|E| = \frac{1}{k_{\max}} \sum_{i_1,...,i_{k_{\max}} \in [\![n+k_{\max}-1]\!]} r_{i_1...i_{k_{\max}}} = \sum_{j=1}^{k_{\max}} \frac{1}{j} \sum_{i_1,...,i_j \in [\![n]\!]} a_{(j)\,i_1...i_j}.$ Hence, combining above with the fact that  $a_{(j)\,i_1...i_j} = \frac{1}{(j-1)!}$  when  $\{v_{i_1},...,v_{i_j}\} \in E$  and 0 otherwise:  $r_{i_1...i_{k_{\max}}} = \frac{1}{(k_{\max}-1)!}$  for nonzero elements of  $R_{k_{\max}}$ .

## Layered e-adjacency hypermatrix

 $R_{k_{\max}}$  is called the layered e-adjacency tensor of the hypergraph  $\mathcal{H}$ . We write it later  $\mathcal{A}_{\mathcal{H}}$ .

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# Finding degrees

It holds:

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$$\begin{split} \sum_{\substack{i_2, \dots, i_{k_{\max}} = 1 \\ \delta_{ii_2} \dots i_{k_{\max}} = 0}}^{n+k_{\max}-1} a_{ii_2 \dots i_{k_{\max}}} = d_i \\ \text{here: } \forall i \in [\![n]\!] : d_i = \deg(v_i) \text{ and } \forall i \in [\![k_{\max} - 1]\!] : d_{n+i} = \deg(y_i) . \\ \text{loreover: } \forall j \in [\![2; k_{\max}]\!] : \\ |\{e : |e| = j\}| = d_{n+j} - d_{n+j-1} \\ \text{nd:} \\ |\{e : |e| = 1\}| = d_{n+1} \end{split}$$

#### Bound for eigenvalues

#### Theorem

The e-adjacency tensor  $\mathcal{A}_{\mathcal{H}}$  has its eigenvalues  $\lambda$  such that:

$$\lambda| \leqslant \max\left(\Delta, \Delta^{\star}\right)$$

where 
$$\Delta = \max_{1 \leq i \leq n} (d_i)$$
 and  $\Delta^* = \max_{1 \leq i \leq k_{\max} - 1} (d_{n+i})$ .

#### Theorem

Let  $\mathcal{H}$  be a r-regular<sup>2</sup> r-uniform hypergraph with no repeated hyperedge. Then this maximum is reached.

(1)

<sup>&</sup>lt;sup>2</sup>A hypergraph is said *r*-regular if all vertices have same degree *r*.

## Quick summary and Future Work

- Layered e-adjacency tensor is easy to build
- Can be stored in |E| elements as it is symmetric
- But inflates spectral bounds
- HUP and PUP: strong basis for further alternatives
- Target: allow repetition => multisets are needed => hb-graphs introduced

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Ouvrard et al. [2018]

Questions?



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